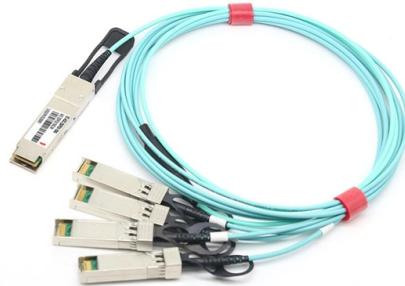


## Motor wiring bridge



### Overview

Despite what may seem complicated at first, the photograph below includes added features such as an LP2954 5V voltage regulator, a bicolor LED, and two switches for testing. One H-bridge drives one motor. For a common two-wheeled robo. Despite what may seem complicated at first, the photograph below includes added features such as an LP2954 5V voltage regulator, a bicolor LED, and two switches for testing. One H-bridge drives one motor. For a common two-wheeled robot, obviously two copies of the H-bridge circuit are needed. (Click the picture above for a movie) 1. Pressing the ri. R1 and R2 are pull-up resistors. These can be any value from 10 kilohm to 100 kilohm. These make sure the inputs are both on unless a signal from the microcontroller tells one or the other to turn off. With both on or both off, the motor doesn't spin because there's no voltage difference between them. Think of these as default values. Unless a diff. IC1 is a dual MOSFET transistor driver chip. Anything from the TC4424 family will do. The MAX4427 and TC4427A is the same but with a lower amperage rating. The IXDN404 has the highest amperage rating (best choice). The DIP part can be purchased at DigiKey or Mouser as part #IXDN404PI. This chip provides two independent inputs that are compatible wit. My original source had D1 and D3 listed as small-signal diodes. I couldn't find any at the time, so, I used 1N5817 Schottky diodes instead. It turns out that Schottky diodes are much better for motor circuits because they react more quickly. The key factors in substitution are: 1. Are the diodes rated to turn on with less voltage than the TC4424's o. D2 and D4 are also Schottky diodes; the same as D1 and D3. D2 and D4 protect the chips from undervoltage (less than ground) by turning on when the voltage in the motor is below GND. Once again, the batteries take care of the problem, rather than power flowing backwards from the chip. D1 through D4 could be eliminated. In fact, Bugdozerruns without.

## Article Content

### H-bridge Circuit for DC Motor Bidirectional Control

This full-bridge, H-bridge, or double half-bridge circuit is commonly used to allow DC motors to rotate forward and backward by selecting the diagonally opposite switching pairs.

### Two Relay DC Motor Control (Simple H-bridge)

In this version, I will show you how to simplify the relay H-bridge, borrowing from an old school wiring technique, sometimes referred to as the California or Chicago 3 way.

### L298N Motor Driver with Arduino - DC Motor Control Guide

In this tutorial, I cover how H-bridge motor control works, how to wire the L298N to an Arduino, and how to write code for direction and speed control with PWM. I also go over power ...

### Lab: Controlling a Stepper Motor With an H-Bridge

The principles in this lab, and the library used, will work with other stepper motors and dual H-bridge drivers as well, though you will have to make some modifications depending in which parts you are ...

### H-Bridge Control Example

H-Bridges are used to control the speed and direction of a motor. They work by controlling the direction of the current flow through the motor. In this example, we will learn how to control an H-Bridge using ...

### H Bridge Motor Control: A Complete Guide for ...

Widely used in robotics, automation, and automotive applications, an H Bridge allows engineers to reverse motor polarity without physically altering ...

### H-Bridge DC Motor Schematic

A schematic and wiring diagram photograph of an example fully-implemented H-Bridge. An H-Bridge circuit allows logic chips (even microcontrollers) to provide power to a DC motor (standard or ...

### H Bridge Motor Control: A Complete Guide for Engineers 2025

Widely used in robotics, automation, and automotive applications, an H Bridge allows engineers to reverse motor polarity without physically altering wiring, making it essential for ...

### Simple H Bridge Motor Driver Circuit Diagram and Working

By combining IRFZ44N and IRF9Z44N MOSFETs, BC547 transistors, and a simple switching mechanism, this H-bridge motor driver circuit is a practical and efficient solution for ...

Interface L298N DC Motor Driver Module with Arduino

It acts as a bridge between your low-power Arduino and your high-power motors. You send small control signals from the Arduino, and the L298N safely handles the higher current ...

How to Build an H-bridge Circuit to Control 2 Motors

In this article, we will go over how to build a H-bridge chip to control 2 motors.

## Contact Us

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